

Problem 1.2

$$\text{For } L = \frac{1}{2}m(\dot{x}^2 + \dot{y}^2 + \dot{z}^2) - U(\sqrt{x^2 + y^2 + z^2})$$

for cylindrical coordinates, we have: $x = s \cos \phi$

$$y = s \sin \phi$$

$$z = z$$

$$\text{then } \dot{x} = \dot{s} \cos \phi - s \sin \phi \dot{\phi} \quad \dot{y} = \dot{s} \sin \phi + s \cos \phi \dot{\phi} \quad \dot{z} = \dot{z}$$

to the kinetic term becomes:

$$\begin{aligned} \dot{x}^2 + \dot{y}^2 + \dot{z}^2 &= \dot{s}^2 \cos^2 \phi - 2s \dot{s} \cos \phi \sin \phi \dot{\phi} + \dot{s}^2 \sin^2 \phi + 2s \dot{s} \sin \phi \cos \phi \dot{\phi} + \dot{z}^2 \\ &+ s^2 \sin^2 \phi \dot{\phi}^2 + s^2 \cos^2 \phi \dot{\phi}^2 \\ &= \dot{s}^2 + \dot{z}^2 + s^2 \dot{\phi}^2 \end{aligned}$$

to for the potential term: $x^2 + y^2 + z^2 = s^2 + z^2$

Then

$$L = \frac{1}{2}m(\dot{s}^2 + \dot{z}^2 + s^2 \dot{\phi}^2) - U(\sqrt{s^2 + z^2})$$

the metric, setting $x^1 = s$, $x^2 = \phi$, $x^3 = z$ is

$$g_{\mu\nu} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & s^2 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Problem 1.1

The two dimensional case suffices to show the pattern:

$$A x = \begin{pmatrix} A^{11} & A^{12} \\ A^{21} & A^{22} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} A^{11} x_1 + A^{12} x_2 \\ A^{21} x_1 + A^{22} x_2 \end{pmatrix} = \begin{pmatrix} A^{ij} x_j \\ A^{ij} x_j \end{pmatrix}$$

so $A x = A^{ij} x_j$, to recover the two elements by setting the open index $i=1, 2$

$$x^T A = (x_1 \ x_2) \begin{pmatrix} A^{11} & A^{12} \\ A^{21} & A^{22} \end{pmatrix} = \begin{pmatrix} x_1 A^{11} + x_2 A^{21} \\ x_1 A^{12} + x_2 A^{22} \end{pmatrix} = \begin{pmatrix} x_j A^{j1} \\ x_j A^{j2} \end{pmatrix} = \begin{pmatrix} A^{i1} x_j \\ A^{i2} x_j \end{pmatrix}$$

$$\text{to } \boxed{x^T A = A^{ij} x_j}$$

Problem 1.3

a.
$$T_{\mu\nu} = \underbrace{\frac{1}{2}[T_{\mu\nu} + T_{\nu\mu}]}_{\equiv S_{\mu\nu}} + \underbrace{\frac{1}{2}[T_{\mu\nu} - T_{\nu\mu}]}_{\equiv A_{\mu\nu}}$$

and we can verify: $S_{\nu\mu} = \frac{1}{2}[T_{\nu\mu} + T_{\mu\nu}] = S_{\mu\nu} \checkmark$

$A_{\nu\mu} = \frac{1}{2}[T_{\nu\mu} - T_{\mu\nu}] = -A_{\mu\nu} \checkmark$

b.
$$T_{\mu\nu} Q^{\mu\nu} = S_{\mu\nu} Q^{\mu\nu} + A_{\mu\nu} Q^{\mu\nu}$$

$$= S_{\mu\nu} Q^{\mu\nu} - A_{\nu\mu} Q^{\mu\nu} = -A_{\nu\mu} Q^{\mu\nu} \xrightarrow{\text{relabel dummy indices}} -A_{\mu\nu} Q^{\mu\nu}$$

$\therefore A_{\mu\nu} Q^{\mu\nu} = -A_{\mu\nu} Q^{\mu\nu} \Rightarrow A_{\mu\nu} Q^{\mu\nu} = 0.$

$$T_{\mu\nu} Q^{\mu\nu} = S_{\mu\nu} Q^{\mu\nu}$$

similarly,
$$T_{\mu\nu} P^{\mu\nu} = S_{\mu\nu} P^{\mu\nu} + A_{\mu\nu} P^{\mu\nu} = A_{\mu\nu} P^{\mu\nu}$$

c. Let $\dot{x}^\nu \dot{x}^\delta \equiv S^{\nu\delta}$, symmetric.

then (2) is: $S^{\nu\delta} \left[\frac{\partial g_{\mu\nu}}{\partial x^\delta} - \frac{1}{2} \frac{\partial g_{\mu\nu}}{\partial x^\mu} \right] \equiv S^{\nu\delta} T_{\mu\nu}$
 + only the portion of $T_{\mu\nu}$ symmetric in $\nu \leftrightarrow \delta$ will survive?

$$T_{\mu\nu} = \frac{1}{2}[T_{\mu\nu} + T_{\nu\mu}] + \frac{1}{2}[T_{\mu\nu} - T_{\nu\mu}]$$

$$= \frac{1}{2} \left[\frac{\partial g_{\mu\nu}}{\partial x^\delta} - \frac{1}{2} \frac{\partial g_{\mu\nu}}{\partial x^\mu} + \frac{\partial g_{\nu\mu}}{\partial x^\delta} - \frac{1}{2} \frac{\partial g_{\nu\mu}}{\partial x^\nu} \right]$$

(since $g_{\nu\mu} = g_{\mu\nu}$)

$$= \frac{1}{2} \left[\frac{\partial g_{\mu\nu}}{\partial x^\delta} + \frac{\partial g_{\nu\mu}}{\partial x^\delta} - \frac{\partial g_{\mu\nu}}{\partial x^\mu} \right]$$

$$\therefore S^{\nu\delta} T_{\mu\nu} = \frac{1}{2} \dot{x}^\nu \dot{x}^\delta \left[\frac{\partial g_{\mu\nu}}{\partial x^\delta} + \frac{\partial g_{\nu\mu}}{\partial x^\delta} - \frac{\partial g_{\mu\nu}}{\partial x^\mu} \right] = \dot{x}^\nu \dot{x}^\delta \left[\frac{\partial g_{\mu\nu}}{\partial x^\delta} - \frac{1}{2} \frac{\partial g_{\mu\nu}}{\partial x^\mu} \right]$$

Problem 1.4

a.
$$m g_{\nu\nu} \ddot{x}^\nu + \frac{1}{2} m \dot{x}^\nu \dot{x}^\nu \left[\frac{\partial g_{\nu\nu}}{\partial x^0} + \frac{\partial g_{\nu\nu}}{\partial x^\nu} - \frac{\partial g_{\nu\nu}}{\partial x^\nu} \right] = - \frac{\partial U}{\partial x^\alpha}$$

For $\alpha=1$, corresponding to the r coordinate:

$$m g_{1\nu} \ddot{x}^\nu + \frac{1}{2} m \dot{x}^\nu \dot{x}^\nu \left[\frac{\partial g_{1\nu}}{\partial x^1} + \frac{\partial g_{1\nu}}{\partial x^\nu} - \frac{\partial g_{1\nu}}{\partial x^1} \right] = - \frac{\partial U}{\partial x^1} \quad (*)$$

the metric, in spherical coordinates, is:

$$g_{\mu\nu} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & r^2 & 0 \\ 0 & 0 & r^2 \sin^2 \theta \end{pmatrix}$$

so the only non-zero terms are g_{11}, g_{22} & g_{33} . Then (*) is

$$m \ddot{x}^1 + \frac{1}{2} m \left(-\dot{x}^2 \dot{x}^2 \frac{\partial g_{33}}{\partial x^1} - \dot{x}^3 \dot{x}^3 \frac{\partial g_{33}}{\partial x^1} \right) = - \frac{\partial U}{\partial x^1}$$

or, using $x^1=r, x^2=\theta, x^3=\phi$:

$$m \ddot{r} + \frac{1}{2} m \left[-\dot{\theta}^2 \cdot 2r - \dot{\phi}^2 \cdot 2r \sin^2 \theta \right] = - \frac{\partial U}{\partial r}$$

$$\boxed{m \ddot{r} - m \left[r \dot{\theta}^2 + r \sin^2 \theta \dot{\phi}^2 \right] = - \frac{\partial U}{\partial r}}$$

b. Starting from $L = \frac{1}{2} m (\dot{r}^2 + r^2 \dot{\theta}^2 + r^2 \sin^2 \theta \dot{\phi}^2) - U(r)$

we have:

$$\frac{d}{dt} \frac{\partial L}{\partial \dot{r}} - \frac{\partial L}{\partial r} = 0$$

$$\frac{d}{dt} \left[m \dot{r} \right] - \frac{1}{2} m (2r \dot{\theta}^2 + 2r \sin^2 \theta \dot{\phi}^2) + \frac{\partial U}{\partial r} = 0$$

or

$$m \ddot{r} - m \left[r \dot{\theta}^2 + r \sin^2 \theta \dot{\phi}^2 \right] = - \frac{\partial U}{\partial r} \text{ as above.}$$